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From the Back Cover

The Development of modern Optimal and robust control theory in the last thirty years calls for significant change in the teaching of classic control. It is the authors' goal to integrate the modern optimal and robust control theory into classical control theory using tools already available from the context of classic control. This book represents the authors' first attempt towards this challenging goal. The book includes a significant portion of the well-known classical control material, albeit with some twists and extensions whenever appropriate in consideration of recent developments and the available modern computational tools. There is significant coverage on some nontraditional topics such as

- Two-degree-of-freedom control
- Kharitonov robust stability results of polynomials
- Performance limitations due to non-minimum phase zeros
- Overshoot and undershoot and their relations with poles/zeros locations
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The book includes the following chapters:

- Modeling and simulation
- Stability and stabilization
- Time domain analysis
- Root locus method
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About the Author

Prof. Li Qiu received the B.Eng degree from Hunan University, Changsha, Hunan, China, in 1981. He received the M.A.Sc. and Ph.D. degrees from the University of Toronto, Toronto, Ont., Canada, in 1987 and 1990, respectively. He joined Hong Kong University of Science and Technology, Hong Kong SAR, China, in 1993, where he is now a professor of Electronic and Computer Engineering. Prof. Qiu's research interests include system, control, information theory, and mathematics for information technology. He served as an associate editor of the IEEE Transactions on Automatic Control and an associate editor of Automatica. He is now a Distinguished Lecturer of IEEE Control Systems Society and the general chair of the 7th Asian Control Conference, which is to be held in Hong Kong in 2009. He is a fellow of IEEE.

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For undergraduate courses in control theory at the junior or senior level.

Introduction to Feedback Control, First Edition updates classical control theory by integrating modern optimal and robust control theory using both classical and modern computational tools. This text is ideal for anyone looking for an up-to-date book on Feedback Control.

Although there are many textbooks on this subject, authors Li Qiu and Kemin Zhou provide a contemporary view of control theory that includes the development of modern optimal and robust control theory over the past 30 years. A significant portion of well-known classical control theory is maintained, but with consideration of recent developments and available modern computational tools.

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An Introductory designed for the research level study

By Troy learns to design

The book is written in 8 years by two authorative researchers in the field of optimal control theory. Although intended as an introductory, this textbook is mathematically sophisticated and self-contained, sometimes reaching to advanced topics. However, I consider it an important feature favoring readers with no engineering control background*.

That being said, the book still provides within 400 or so pages lots of examples along with matlab codes which helps you to create a more intuitive understanding of key concepts. You will appreciate the appropriateness in the choice of engineering examples and information provided. Another great feature of the

book is that it provides a great up-to-date references to important articles and books which, in an ideal situation, should be read to improve the learning process. So this is a fivestar textbook which deserves to be read from page one to last.

(*In my personal view, the way people learn control theory (or anything else) is a process of creating a simulation in their minds rather than on a computer. The more sophisticated mind is simply capable of handling more complex simulation...If you have lots of engineering experience, you have certainly seen how a control system actually works. Then you should have no problem creating a visual simulation in your mind. For those who has no engineering control background, mathematical simulation is the second best choice...Its safe to say most theoretical researchers in this field are more or less creating all sorts of simulations in their minds everyday, hoping that some of them will actually find an application...)

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Like new

By Jie

I am no control background, so this book is very suitable for me. I strongly recommend that people who has no control knowledge buy this book first and then begin your study. Thank you.

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